

- $X(0) = 0$;
- for $\tau > 0$, $Y_\tau = X(t + \tau) - X(t)$ is a normal (Gaussian) random variable with mean 0 and variance $\alpha\tau$;
- Y_τ is independent of $X(t')$ for all $t' \leq t$.

Definition. $X(t)$ is a Brownian motion process if

Think about that $X(t)$ is a position of a particle at time instance t , and $X(t)$ may not be nondecreasing with time.

Note. A Poisson process is a continuous time and discrete value process. A Brownian process is a continuous time and continuous value process.

R. Brown (1827, a botanist) studied the motion of pollen particles suspended in water and lent him name to the type of erratic movements.

The Brownian Motion Process

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$$f_{Y_\tau}(x) = \frac{1}{\sqrt{2\pi\alpha\tau}} e^{-\frac{x^2}{2\alpha\tau}}, -\infty < x < \infty$$

2. The pdf of Y_τ is given by

Thus $X(t)$ can be viewed as a random walk on a line. After a time step τ , the particle's position has moved by an amount Y_τ that is independent of the previous position $X(t)$.

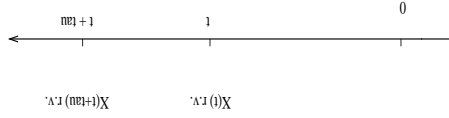
$$X(t + \tau) = X(t + \tau) - X(t) + X(t) \\ = Y_\tau + X(t)$$

1. We can write

Remark:

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It is, in general, a function of time.

$$\mu_X(t) = E[X(t)].$$

Definition 1 The expected value (or mean) of a stochastic process $X(t)$ is the expected value of the r.v. $X(t)$:

Expected Values, Autocovariance and Autocorrelation

	increases	1 →
an observation of $X(t)$ provides an accurate indication of the values of $X(t + \tau)$ (since they tend to have a linear relation)	decreases	0 →
Relation	$ \rho(X(t), X(t + \tau)) = Cov(X(t), X(t + \tau)) $	
$\rho(X(t), X(t + \tau)) = \frac{Cov(X(t), X(t + \tau))}{\sqrt{Var(X(t))Var(X(t + \tau))}}$		

Recall that covariance of two random variables X and Y indicate that how much information random variable X (or Y) provides about Y (or X).

Autocovariance and Autocorrelation

Example 1 We continue the Example in Sec. 1. At the receiver of an AM radio, the received signal contains a cosine carrier signal at the carrier frequency f_c with a random phase Θ that is uniformly distributed over $[-\pi, \pi]$. The received signal is

$$X(t) = A \cos(2\pi f_c t + \Theta)$$

Find the expectation and the autocorrelation of $X(t)$.

Definition 2 The autocovariance $\text{Cov}_X(t, \tau)$ of $X(t)$ is the covariance of the r.v. $X(t)$ and $X(t + \tau)$:

$$\text{Cov}_X(t, \tau) = \text{Cov}_X(X(t), X(t + \tau)).$$

Definition 3 The autocorrelation $R_X(t, \tau)$ of a process $X(t)$ is the joint moment of the r.v. $X(t)$ and $X(t + \tau)$:

$$R_X(t, \tau) = E[X(t), X(t + \tau)].$$

Theorem 1 The autocovariance and autocorrelation of $X(t)$ are related as follows

$$\text{Cov}_X(t, \tau) = R_X(t, \tau) - \mu_X(t)\mu_X(t + \tau)$$

Remark. If $\tau = 0$, then $\text{Cov}_X(t, 0) = \text{Var}(X(t))$. In other words, the variance of the r.v. $X(t)$ is given by

$$\text{Var}(X(t)) = \text{Cov}_X(t, 0) = R_X(t, 0) - (\mu_X(t))^2$$